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A Parallel, Fourier Finite-Element Formulation with an Iterative Solver for the Simulation of 3D LWD Measurements Acquired in Deviated Wells

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OVERVIEW

- 1. Motivation: Simulation of logging-while-drilling (LWD) measurements acquired in deviated wells.
- 2. Method:
 - Fourier-finite-element formulation in a non-orthogonal system of coordinates.
 - Goal-oriented self-adaptive *hp*-FE method.
- 3. Iterative solver.
- 4. Numerical simulation of LWD measurements.
- 5. Conclusions and future work.

MOTIVATION (LOGGING-WHILE-DRILLING)



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3D Variational Formulation

Time-Harmonic Maxwell's Equations

 $\begin{aligned} \nabla \times \mathbf{H} &= \mathring{\sigma} \mathbf{E} + \mathbf{J}^{imp} & \mathsf{Ampere's law} \left(\mathring{\sigma} &= \sigma + j \omega \epsilon \right) \\ \nabla \times \mathbf{E} &= \mathring{\mu} \mathbf{H} + \mathbf{M}^{imp} & \mathsf{Faraday's law} \left(\mathring{\mu} &= -j \omega \mu \right) \\ \nabla \cdot \left(\epsilon \mathbf{E} \right) &= \rho & \mathsf{Gauss' law of Electricity} \\ \nabla \cdot \left(\mu \mathbf{H} \right) &= 0 & \mathsf{Gauss' law of Magnetism} \end{aligned}$

E-VARIATIONAL FORMULATION:

Find
$$\mathbf{E} \in \mathbf{E}_{\Gamma_{E}} + \boldsymbol{H}_{\Gamma_{E}}(\operatorname{curl}; \Omega)$$
 such that:
 $\langle \nabla \times \mathbf{F}, \mathring{\mu}^{-1} \nabla \times \mathbf{E} \rangle_{L^{2}(\Omega)} - \langle \mathbf{F}, \mathring{\sigma} \mathbf{E} \rangle_{L^{2}(\Omega)} = \langle \mathbf{F}, \mathbf{J}^{imp} \rangle_{L^{2}(\Omega)}$
 $- \langle \mathbf{F}_{t}, \mathbf{J}_{\Gamma_{H}}^{imp} \rangle_{L^{2}(\Gamma_{H})} + \langle \nabla \times \mathbf{F}, \mathring{\mu}^{-1} \mathbf{M}^{imp} \rangle_{L^{2}(\Omega)} \quad \forall \mathbf{F} \in \boldsymbol{H}_{\Gamma_{E}}(\operatorname{curl}; \Omega)$

E-Variational Formulations (Cylindrical Coordinates)

FINITE ELEMENT — 3D—:

$$\begin{cases} \mathsf{Find} \ \mathrm{E} \in \mathrm{E}_{\Gamma_E} + \boldsymbol{H}_{\Gamma_E}(\mathrm{curl};\Omega) \ \mathsf{such that:} \\ \left\langle \boldsymbol{\nabla} \times \mathrm{F}, \mathring{\mu}^{-1} \boldsymbol{\nabla} \times \mathrm{E} \right\rangle_{L^2(\Omega)} - \left\langle \mathrm{F}, \mathring{\sigma} \mathrm{E} \right\rangle_{L^2(\Omega)} = \left\langle \mathrm{F}, \mathrm{J}^{imp} \right\rangle_{L^2(\Omega)} \\ - \left\langle \mathrm{F}_t, \mathrm{J}_{\Gamma_H}^{imp} \right\rangle_{L^2(\Gamma_H)} + \left\langle \boldsymbol{\nabla} \times \mathrm{F}, \mathring{\mu}^{-1} \mathrm{M}^{imp} \right\rangle_{L^2(\Omega)} \ \forall \ \mathrm{F} \in \boldsymbol{H}_{\Gamma_E}(\mathrm{curl};\Omega) \end{cases}$$

FOURIER FINITE ELEMENT — 3D = Sequence of Coupled 2D Problems—:

$$\begin{split} \left[\begin{array}{l} \mathsf{Find} \ \mathrm{E} &= \frac{1}{\sqrt{2\pi}} \sum_{n=-\infty}^{\infty} \mathcal{F}_n(\mathrm{E}) \ e^{jn\phi}, \text{where for each } n: \\ \mathcal{F}_n(\mathrm{E}) \in \mathcal{F}_n(\mathrm{E}_{\Gamma_{E,1D}}) + H_{\Gamma_{E,1D}}(\mathrm{curl}^n;\Omega_{2D}), \text{ and} \\ &\sum_{m=-\infty}^{\infty} \left\langle \nabla^n \times \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\mu}^{-1}) \nabla^m \times \mathcal{F}_m(\mathrm{E}) \right\rangle_{L^2(\Omega_{2D})} - \left\langle \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\sigma}) \mathcal{F}_m(\mathrm{E}) \right\rangle_{L^2(\Omega_{2D})} \\ &= \left\langle \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_n(\mathrm{J}^{imp}) \right\rangle_{L^2(\Omega_{2D})} - \left\langle \mathcal{F}_n(\mathrm{F}_t) \ , \ \mathcal{F}_n(\mathrm{J}^{imp}_S) \right\rangle_{L^2(\Gamma_{H,1D})} \\ &+ \sum_{m=-\infty}^{\infty} \left\langle \nabla^n \times \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\mu}^{-1}) \mathcal{F}_m(\mathrm{M}^{imp}) \right\rangle_{L^2(\Omega_{2D})} \ \forall \ \mathcal{F}_n(\mathrm{F}) \in H_{\Gamma_{E,1D}}(\mathrm{curl}^n;\Omega_{2D}) \end{split}$$

Cartesian system of coordinates: x = (x, y, z). New non-orthogonal system of coordinates: $\zeta = (\zeta_1, \zeta_2, \zeta_3)$.





Subdomain I;Subdomain II;Subdomain III $\begin{cases} x = \zeta_1 \cos \zeta_2 \\ y = \zeta_1 \sin \zeta_2 \\ z = \zeta_3 \end{cases}$; $\begin{cases} x = \zeta_1 \cos \zeta_2 \\ y = \zeta_1 \sin \zeta_2 \\ z = \zeta_3 + \tan \theta_0 \frac{\zeta_1 - \rho_1}{\rho_2 - \rho_1} \rho_2 \end{cases}$;; $\begin{cases} x = \zeta_1 \cos \zeta_2 \\ y = \zeta_1 \sin \zeta_2 \\ z = \zeta_3 + \tan \theta_0 \zeta_1 - \rho_1 \\ z = \zeta_3 + \tan \theta_0 \zeta_1 \end{cases}$;

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E-Variational Formulation in the New System of Coordinates ζ

In the new system of coordinates, we obtain:

3D FOURIER FINITE ELEMENT FORMULATION

- Sequence of "Weakly" Coupled 2D Problems -

$$\begin{split} & \mathsf{Find} \ \mathrm{E} = \frac{1}{\sqrt{2\pi}} \sum_{n=-\infty}^{\infty} \mathcal{F}_n(\mathrm{E}) \ e^{jn \zeta_2}, \mathsf{where for each } n: \\ & \mathcal{F}_n(\mathrm{E}) \in \mathcal{F}_n(\mathrm{E}_{\Gamma_{E,1D}}) + H_{\Gamma_{E,1D}}(\mathrm{curl}^n;\Omega_{2D}), \ \mathsf{and} \\ & \sum_{\substack{m=-2\\m=-2}}^{2} \left\langle \nabla^n \times \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\mu}_{mod}^{-1}) \nabla^m \times \mathcal{F}_m(\mathrm{E}) \right\rangle_{L^2(\Omega_{2D})} - \left\langle \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\sigma}_{mod}) \mathcal{F}_m(\mathrm{E}) \right\rangle_{L^2(\Omega_{2D})} \\ & = \left\langle \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_n(\mathrm{J}^{imp}) \right\rangle_{L^2(\Omega_{2D})} - \left\langle \mathcal{F}_n(\mathrm{F}_t) \ , \ \mathcal{F}_n(\mathrm{J}_S^{imp}) \right\rangle_{L^2(\Gamma_{H,1D})} \\ & + \sum_{\substack{m=-2\\m=-2}}^{2} \left\langle \nabla^n \times \mathcal{F}_n(\mathrm{F}) \ , \ \mathcal{F}_{n-m}(\mathring{\mu}_{mod}^{-1}) \mathcal{F}_m(\mathrm{M}^{imp}) \right\rangle_{L^2(\Omega_{2D})} \quad \forall \ \mathcal{F}_n(\mathrm{F}) \in H_{\Gamma_{E,1D}}(\mathrm{curl}^n;\Omega_{2D}) \end{split}$$

Five Fourier modes are sufficient to represent EXACTLY the new material coefficients resulting from incorporating the change of coordinates.

Main Advantages

Using this non-orthogonal system of coordinates, we obtain:

- Subdomain I : $\mathcal{F}_{n-m}(\mathring{\mu}^{-1}) = \mathcal{F}_{n-m}(\mathring{\sigma}^{-1}) = 0 \quad \forall \ |n-m| > 0$ (uncoupled 2D problems).
- Subdomain II : $\mathcal{F}_{n-m}(\mathring{\mu}^{-1}) = \mathcal{F}_{n-m}(\mathring{\sigma}^{-1}) = 0 \quad \forall \ |n-m| > 2$ (penta-diagonal coupling).
- Subdomain III : $\mathcal{F}_{n-m}(\mathring{\mu}^{-1}) = \mathcal{F}_{n-m}(\mathring{\sigma}^{-1}) = 0 \quad \forall \ |n-m| > 1$ (tri-diagonal coupling).

SEVERAL SYSTEMS OF COORDINATES THAT LEAD TO A SIGNIFICANT COMPLEXITY REDUCTION CAN BE CONSTRUCTED FOR MANY GEOMETRIES ARISING IN CHALLENGING GEOPHYSICAL APPLICATIONS.

Model Problem

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Verification

Logging Instrument in a Homogeneous Formation



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Verification



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Verification



Verification



Verification



Verification



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SELF-ADAPTIVE GOAL-ORIENTED HP-FEM

A Self-Adaptive Goal-Oriented *hp*-FEM

Optimal 2D Grid (Through Casing Resistivity Problem)



We vary locally the element size h and the polynomial order of approximation p throughout the grid.

Optimal grids are automatically generated by the computer.

The self-adaptive goal-oriented hp-FEM provides exponential convergence rates in terms of the CPU time vs. the error in a user prescribed quantity of interest.

ITERATIVE SOLVER

Description and Performance of the Iterative Solver

Block-Jacobi Preconditioner

Krylov subspace optimization method (CG or GMRES).

The block Jacobi preconditioner consists of a 2.5D problem defined by ignoring the couplings ocurring between the different Fourier basis functions in the original problem.



This simple iterative solver enables fast computations.

NUMERICAL RESULTS: LWD



NUMERICAL RESULTS: LWD



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NUMERICAL RESULTS: LWD



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NUMERICAL RESULTS: LWD

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NUMERICAL RESULTS: LWD

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NUMERICAL RESULTS: LWD

60-Degree Deviated Well

LWD, 2 Mhz

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CONCLUSIONS AND FUTURE WORK

Conclusions

- A Fourier-Finite-Element method in a non-orthogonal system of coordinates provides enhanced performance for simulating logging-while-drilling measurements in deviated wells.
- A simple iterative solver based on solving exactly a 2.5D problem provides excellent performance, even in presence of elongated elements and/or highly varying material properties.

Future Work

- Inversion
- Multi-physics
- Marine controlled source EM applications.

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